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Evaluation of an algorithm to choose between competing models of respiratory mechanics

Abstract: Model based decision support helps in optimizing therapy settings for individual patients while providing additional insight into a patient's disease state through the identified model parameters. Using multiple models with different simulation focus and complexity allows adapting decision support to the current clinical situation and the available data. A previously presented set of numerical criteria allows selecting the best model based on fit quality, model complexity, and how well the parameter values are defined by the presented data. To systematically evaluate those criteria in an algorithm we have created in-silico data sets using four different respiratory mechanics models with three different parameter settings each. Each of those artificial patients was ventilated with three different manoeuvres and the resulting data was used to identify the same models used to create the data. The selection algorithm was then presented with the results to select the best model. Not considering determinateness of the identified model parameters, the algorithm chose the same model that was used to create the data in 78%, a more complex model in 5% and a less complex model in 18% of all cases. When including the determinateness of model parameters in the decision process, the algorithm chose the same model in 42% of the cases and a less complex model in 56% of all cases. In 2% of the presented cases, no model complied with the required criteria.

Keywords: Medical decision support; physiological modelling; respiratory mechanics; model selection

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1 Introduction

Mechanical ventilation is a routinely applied therapy that can be life-saving in patients that are not able to maintain sufficient oxygenation and carbon dioxide removal. However, the application of mechanical ventilation bears the risk of ventilator induced lung injury (VILI) if ventila-

tor settings are set inappropriately [1]. Mathematical models can be individualized to reflect a patient's pathophysiological characteristics and can thus be implemented in medical decision support systems where they are used to predict patient reaction to changes in therapy settings. To enable a decision support system to adapt to changes in the clinical scenario it needs to be provided with a model that is able to simulate various pathologies. Individualization of such complex models is usually challenging as the available data at the bedside might not be sufficient to robustly identify all model parameters. Providing multiple models differing in complexity and simulation focus is thus advantageous. Various models are described in literature [2–6] comprising various pathologies, a different numbers of model parameters and are thus of different mathematical complexity. Based on the current clinical question and the available data to identify the models, the decision support system should then be able to select the model that fits the current situation best. This decision should be based on numerical criterias describing the eligibility of the models to choose from.

We have previously presented multiple criteria that allow evaluating models based on fit quality, model complexity and the determinateness of the model parameters [6] and have presented preliminary results on ten mechanically ventilated patients [7]. However, a systematic evaluation of the algorithms performance has not been presented so far and should thus be described below.

2 Methods

2.1 Selection algorithm

The presented algorithm employs three numerical criteria describing the ability of a model to reproduce a given data set. The criteria are described in short below.

Coefficient of Determination (CD): CD describes how well a model is able to reproduce a given data set with 1 denoting perfect agreement and 0 showing that there is no correlation between model results and the data. CD is calculated as [2]:

$$CD = 1 - \frac{SSE}{\sum_{i=1}^n (y_{data_i} - \bar{y}_{data})^2} \quad (1)$$

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with SSE denoting the summed squared differences between simulated and measured results ($ydata$). $y\bar{data}$ is the mean of $ydata$, n is the number of samples.

Corrected Akaike Information Criterion (AICc): The AICc allows identifying the model that has the maximum likelihood of describing a given data set while trading off between goodness-of-fit and the number of parameters that are adaptable. Lower values are preferred. AICc identifies which is the best among a given set models. The calculated values are thus not absolute and provide no information about how well a model reproduces the given data. The AICc is calculated as [8, 9]:

$$AICc = 2m + n \left[\ln \left(2\pi \frac{SSE}{n} + 1 \right) \right] + \frac{2m(m+1)}{n-m-1} \quad (2)$$

with m denoting the number of model parameters.

Confidence Interval (CI): The confidence intervals provide information about how well each model parameter is defined by the data. Large CI indicate that the parameter values are highly uncertain. CI were determined using the *nlparci* function in MATLAB (R2012a, The Mathworks, Natick, USA) which returns a range in which the parameter values are with a probability of 95%. All CI were normalized to their respective parameter value (relative CI, *rCI*).

the model with highest CD and all models within 2% of that CD are selected for the next stage. From the selected models, the model with lowest AICc is then selected and the *rCI* of all parameters is checked. If one is above 20%, the model is eliminated and the model with next best AICc is checked. If no model with sufficient CI is found, the algorithm selects the remaining models with $CD \geq 0.8$ and ranks them again with respect to AICc. If CI is critical for all those models as well, model selection fails and no model is selected.

2.2 Artificial patient data and evaluation

We have used four models of respiratory mechanics with different complexity and a different number of identifiable parameters. The applied models are a trivial model of first order with one resistance and one compliance (*FOM*) comprising two parameters (resistance R and compliance C), a viscoelastic model (*VEM*) comprising four parameters (resistances R_1 and R_2 , compliances C_1 and C_2) [10], a model to simulate pressure dependent alveolar recruitment (*PRM*) with five parameters (R , C , threshold opening pressure TOP , number of opened alveoli at the onset of inspiration $NOpen$, overdistension parameter K) [11], and a model to simulate both viscoelastic behaviour and recruitment (*PRVEM*) comprising seven parameters (R_1 , R_2 , C_1 , C_2 , TOP , $NOpen$, K) [12].

Three different parameter sets for each model were created to simulate healthy patients and different stages of lung disease. Each of those 12 artificial patients was ventilated with three different ventilation manoeuvres, each with three different flow rates. The applied ventilation manoeuvres were:

- **Low-Flow (LF):** low and constant inspiration flow of 30 to 40 ml/s for 50 seconds. This manoeuvre is applied to determine quasi-static pressure-volume dependencies.
- **Dynamic-Slice (DS):** high and constant inspiration flow of 350 to 500 ml/s for 1.5s. This manoeuvre is applied to determine dynamic lung properties.
- **Static Compliance Automated Single Step (SCASS):** volume controlled ventilation cycle with inspiration flows of 500 to 600 ml/s for 1s and a prolonged inspiratory pause of 5s. SCASS is applied to determine equilibration processes in the lung tissue under a quasi-static pressure-volume relation.

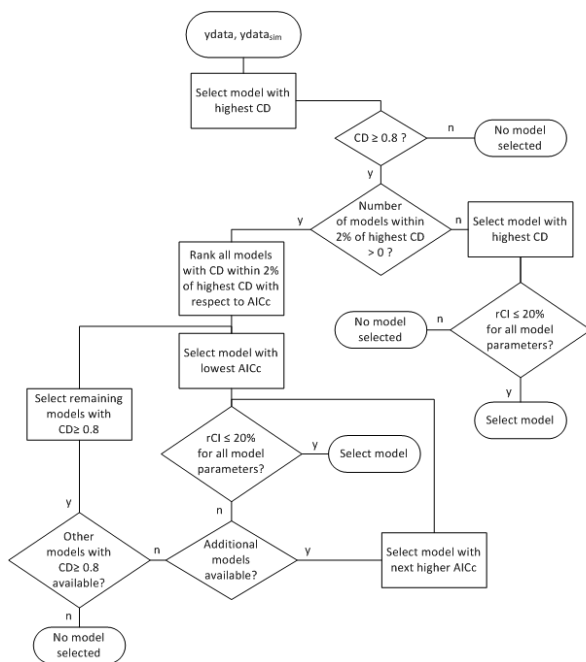


Figure 1: Model selection algorithm. $ydata$ – recorded patient data, $ydata_{sim}$ – model simulated data.

Figure 1 shows a flow diagram of the selection algorithm. CD values serve as primary selection parameter, as

In total, 108 data sets were created and modified by adding white noise with an amplitude of 5% of the respective data point. Each of the four respiratory mechanics models was

then fitted to each of the data sets using a hierarchical identification approach [10, 12]. It uses the identified parameter values of less complex models as initial guesses when identifying the more complex models. It thus does not require any initial guesses and ensures optimal identification outcome. The model results were then fed to the presented algorithm to select the model that fits the given data best.

3 Results

Figure 2 shows simulated response to the described manoeuvres for all four models compared to artificial patient data created using the PRVEM. In LF results, the PRVEM had best CD and AICc, however CI was critical in two parameters, leading to the algorithm to select VEM. In DS data, the PRVEM again had best CD and AICc, however CI was critical in five parameters, leading to FOM being the selected model. The SCASS results showed highest CD and lowest AICc in VEM, thus this being the selected model.

Tables 1 and 2 show which model was selected compared to which model was used to create the data. Table 1 shows results when CI of the model parameters is not included in the selection process, while Table 2 shows results when CI is included as a criteria.

When omitting the CI criteria, the same model as used to create the data was selected by the algorithm in 84 of 108 cases. In 5 cases, a more complex model was selected due to a lower AICc and in 19 cases a less complex model was selected due to the same reason.

When including the CI criteria, the same model was selected in 45 out of the 108 cases. A more complex model was never selected, while a less complex model was selected in 61 cases (8 cases because of lower AICc, 53 cases because CI was critical in other models). No selection at all was conducted in 2 cases, all due to critical CI values in every model with $CD \geq 0.8$.

4 Discussion

Using multiple models in decision support allows adaption to

a change in the clinical scenario and to the patient data available at the bedside. In cases where detailed measurements are available, complex models can be identified, while simple models are applied if less information is available. The presented algorithm should enable the decision support system to select the model that fits the given

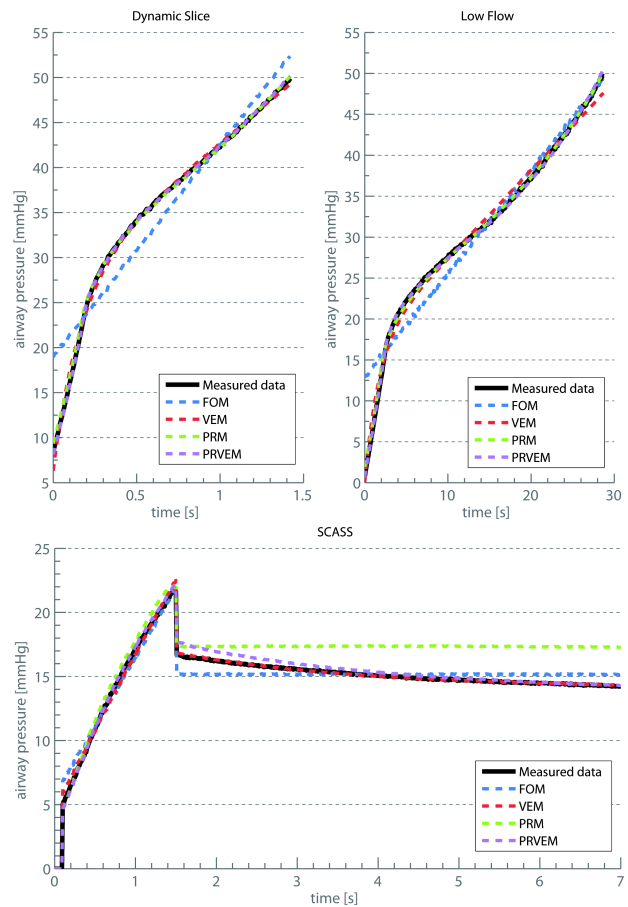


Figure 2: Exemplary results for model simulated results fitted to artificial patient data.

data best with the smallest number of parameters while ensuring the correctness of the identified parameter values.

When omitting the CI criteria, i.e. the algorithm does not check if the parameter values of a model are sufficiently defined by the data, the algorithm selected the correct model, i.e. the model that was used to create the data, in 78% of all cases. In 18% of the cases, a less complex model was selected, i.e. the data could be reproduced with sufficient accuracy while using less model parameters. In data created with the PRM, five cases led to the algorithm to select the PRVEM, i.e. a more complex model. In those cases, parameter identification failed to find the correct PRM parameters thus leading to the simulation results to slightly deviate from the presented data. Here, identification procedure should be improved.

When including the CI criteria, the algorithm was able to select the correct model in 42% of all cases. In 56% of the cases, a less complex model was selected either due to having a comparable accuracy using less parameters (7%

Table 1: Results of model selection when CI is not evaluated.

	Same model selected	More complex model selected		Less complex model selected		No model selected because of $CD < 0.8$
		Lowest AICc	Only model with $CD > 0.8$	Lowest AICc	Only model with $CD > 0.8$	
FOM	27	0	0	-	-	0
VEM	24	0	0	3	0	0
PRM	16	5	0	6	0	0
PRVEM	17	-	-	10	0	0
Total	84	5	0	19	0	0

Table 2: Results of model selection when CI is evaluated.

	Same model selected	More complex model selected			Less complex model selected			No model selected	
		Lowest AICc	Only model with $CD > 0.8$	CI critical in other models	Lowest AICcs	Only model with $CD > 0.8$	CI critical in other models	All $CD < 0.8$	All CI critical
FOM	27	0	0	0	-	-	-	0	0
VEM	18	0	0	0	3	0	6	0	0
PRM	0	0	0	0	3	0	24	0	0
PRVEM	0	-	-	-	2	0	23	0	2
Total	45	0	0	0	8	0	53	0	2

total) or due to CI being critical in the higher ranked models (49% total). CD being below 0.8 in all but one model or in all models was never the case, leading to the assumption that the identification routine is robust. No model was selected in 2% of the cases, all due to CI being critical in every model with $CD \geq 0.8$. Thus, except for those two cases, all models are able to reproduce the presented data with acceptable accuracy.

The presented algorithm thus allows selecting the model that is able to reproduce the recorded patient data with sufficient accuracy with the lowest number of parameters possible. Both tests (with CI criteria and without it) showed that the algorithm is able to find the model that was used to create the data or a model that fits the data with comparable accuracy while being less complex in an acceptable number of cases (95% of cases when CI is neglected, 49% with CI criteria). Additionally, the algorithm ensures that the identified parameters may be trusted by checking if the information contained in the recorded data is sufficient to define the parameter values. Here, results showed that in more complex models (PRM and PRVEM), CI is almost always critical in at least one parameter, leading to a less complex or no model being selected. We conclude that identifying models of higher complexity it may be insufficient to apply only one manoeuvre. Future work is planned to investigate which manoeuvres prove to be beneficial for the identification of which parameter in

those models.

Author's Statement

Conflict of interest: Authors state no conflict of interest. Material and Methods: Informed consent: Informed consent has been obtained from all individuals included in this study. Ethical approval: The research related to human use has been complied with all the relevant national regulations, institutional policies and in accordance the tenets of the Helsinki Declaration, and has been approved by the authors' institutional review board or equivalent committee.

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